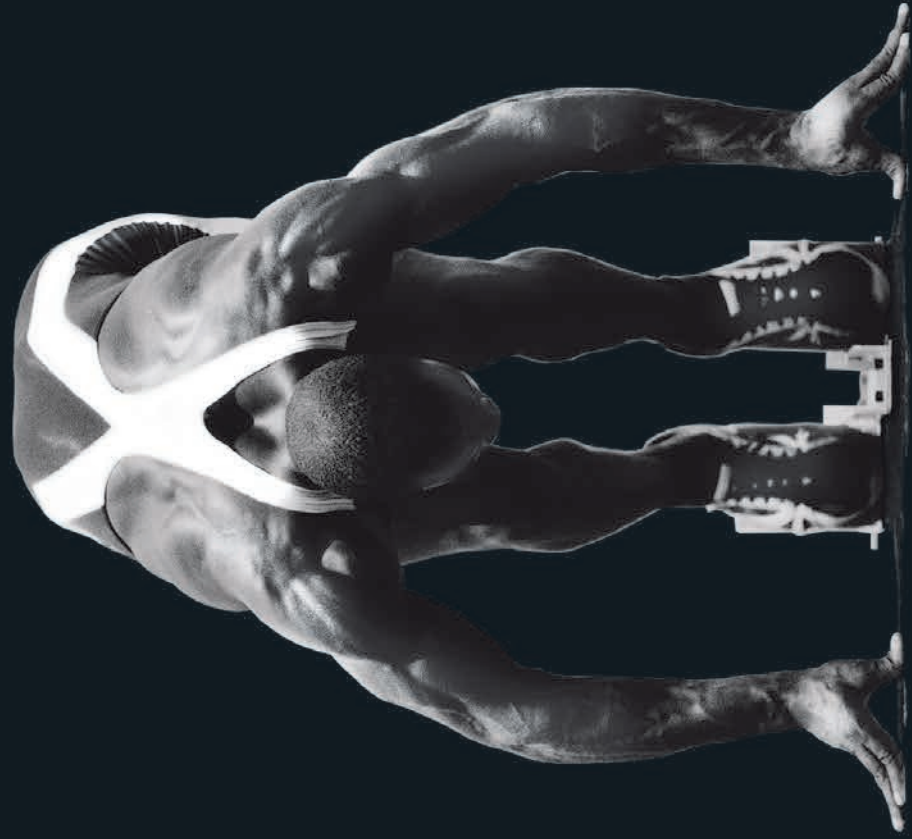


# *isnav*

NAVIGATOR AND TIME SERVER



## VEHICULAR NAVIGATOR AND TIME SERVER

The *isnav* vehicular navigation system is the **advanced navigation and time reference solution of GMV** for military vehicles. *isnav* provides data about position, speed, attitude and time in various formats in order to offer an integrated navigation and synchronization solution. The *isnav* system is ready to include the **PRESENCE 2 Public Regulated Service (PRS) Galileo receiver** and may integrate an **Inertial Navigation System (INS)**. The **time server** unit of *isnav* can be extended to provide synchronization signals in various formats such as IRG-B or HQ.

*isnav* has been chosen by the Spanish Ministry of Defense for the VCR 8x8 program.

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INNOVATING SOLUTIONS

# isnav

## NAVIGATOR AND TIME SERVER

The **isnav** vehicular navigation system is the **advanced navigation and time reference solution of GMV** for military vehicles. **isnav** incorporates multiconstellation (GPS, Galileo and GLONASS) satellite navigation technology and is **ready to include the PRESENCE 2 Public Regulated Service Galileo receiver**. It offers compatibility with external Inertial Navigation Systems (INS) for a robust navigation in covered areas or operation theaters under satellite navigation denial (strong jamming). The multiconstellation technology, the PRS compatibility and the external INS aiding provide a **robust navigation solution** and a **spoofing immunity** in the state of the art.

**isnav** can also be used as the **time source for the vehicle network**. **isnav** implements an NTP time server for the synchronization of the vehicle systems and provides a 1PPS

output paired with NMEA messages, for those equipment requiring a higher timing accuracy. If it is required to provide timing signals in alternative formats, such as IRG-B or HQ, **isnav** may be extended with the time module developed for GMV SENDA navigation system, to be included in the new Spanish F110 frigates. This additional time module provides a high stability oscillator to serve as a robust time reference in absence of GNSS signals.

The **modular design** of **isnav** allows the adaptation to diverse external INS units, with tailored precision matching the application, and to different mission system requirements. **isnav** provides a standard data output based on NMEA messages and an extended proprietary binary output that allow the time, position, speed and orientation be exploited by various vehicle configurations.

<b>Supplied data - Navigation</b>	<ul style="list-style-type: none"> <li>Position: latitude, longitude and altitude</li> <li>Speed: horizontal, drift angle and vertical</li> <li>Attitude: yaw, pitch and roll</li> </ul>
<b>Supplied data - Timing</b>	<ul style="list-style-type: none"> <li>Time: UTC and local</li> <li>NTP server</li> <li>1PPS signal</li> <li>Optional: Time distribution module with IRIG-B, HQ signals and high stability oscillator for time propagation in absence of GNSS signal</li> </ul>
<b>I/O ports</b>	<ul style="list-style-type: none"> <li>2 x Ethernet 10/100 I/O</li> <li>1 x CAN (J1939) input</li> <li>1 x RF GNSS input</li> <li>1 x RF GNSS auxiliary output</li> <li>1 x 1PPS output</li> <li>1 x PRS key loading port</li> <li>5 x Configurable discrete outputs</li> <li>2 x Configurable discrete inputs</li> <li>1 x PRS zeroize discrete input</li> <li>1 x Maintenance port</li> </ul>
<b>Logic I/O interfaces</b>	<ul style="list-style-type: none"> <li>Advanced data and command interface interoperable with the VCR 8x8 mission system</li> <li>Navigation data according to NMEA 0183 (v. 4.1)</li> <li>CAN odometer (J1939)</li> <li>NTP server</li> </ul>
<b>isnav-INS interface</b>	<ul style="list-style-type: none"> <li>2 x RS232</li> <li>1 x 1PPS</li> <li>1 x CAN (J1939)</li> <li>1 x Power supply for INS (28 V)</li> </ul>
<b>Power supply</b>	<ul style="list-style-type: none"> <li>28 V (MIL-STD-1275E)</li> <li>&lt; 20 W (without PRS)<sup>1</sup></li> </ul>
<b>Size and weight</b>	<ul style="list-style-type: none"> <li>258 x 177 x 99 mm</li> <li>&lt; 4.5 Kg (without PRS)</li> </ul>

<b>Enclosure</b>	<ul style="list-style-type: none"> <li>Mechanized aluminum (painted to vehicle specification)</li> <li>Military connectors: <ul style="list-style-type: none"> <li>- MIL-DTL-38999</li> <li>- MIL-STD-348</li> </ul> </li> </ul>
<b>Qualification</b>	<ul style="list-style-type: none"> <li>Temperature: C1 (intermediate cold) y A1 (extreme heat), AECTP-200-4</li> <li>Humidity: MIL-STD-810G (M. 507.5 P. II)</li> <li>Fungus: MIL-STD-810G</li> <li>Corrosion: ISO9227:2012 (240h)</li> <li>Vibration: MIL-STD-810G (Ground Vehicle)</li> <li>Shock: MIL-STD-810G (Crash Hazard Shock Test)</li> <li>Rain: MIL-STD-810G (M. 506 P. III)</li> <li>EMI/EMC: MIL-STD-461F</li> <li>Bonding/Grounding: MIL-STD-464C</li> </ul>
<b>GNSS antenna</b>	<ul style="list-style-type: none"> <li>Low profile ruggedized multiconstellation active antenna: <ul style="list-style-type: none"> <li>- Direct solar radiation: A1 from MIL-STD-810G (M. 505.5 P. I)</li> <li>- Lightning: AECTP-250 ED CV.1</li> </ul> </li> </ul>



<sup>1</sup>Calculated for an average INS, it could vary depending on the INS model chosen for the configuration.